IN THE CLAIMS

Please amend the claims as follows:

Claims 1-11 (Canceled).

Claim 12 (New): An agricultural mower comprising:

at least one frontal working unit configured to cut a standing product;

at least one lateral working unit configured to cut a standing product;

connecting devices configured to connect the working units to a motor vehicle, at least one of the connecting devices allowing the corresponding working unit to move transversely during work with respect to a direction of forward travel of the mower;

an operating member configured to cause the transverse movement of the at least one working unit; and

a control device configured to control the operating member;

wherein the control device comprises a sensor configured to measure a roll angle of the mower and a driving unit processing information from the sensor and controlling a distributor configured to act on the operating member so as to move the at least one lateral working unit transversely to keep a cutting overlap at an optimum value.

Claim 13 (New): A mower as claimed in Claim 12, wherein the connecting device for connecting the at least one lateral working unit comprises a front part configured to be connected to the motor vehicle and a rear part to which the at least one working unit is connected, wherein the front part and the rear part are connected to one another by link rods defining a deformable quadrilateral.

Claim 14 (New): A mower as claimed in Claim 13, wherein the link rods define a trapezium converging towards the front.

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Claim 15 (New): A mower as claimed in Claim 13, wherein the rear part supports two working units.

Claim 16 (New): A mower as claimed in Claim 13, wherein the operating member is connected to the front part and to the rear part.

Claim 17 (New): A mower as claimed in Claim 12, wherein the connecting device for connecting the at least one lateral working unit comprises a chassis resting on the ground by wheels and to which the working unit is connected, a hitching head configured to be connected to the motor vehicle, and a drawbar connected at each of its ends to the chassis and the hitching head by a respective articulation having an axis directed upwards.

Claim 18 (New): A mower as claimed in Claim 17, wherein the operating member is connected to the chassis and to the drawbar.

Claim 19 (New): A mower as claimed in Claim 12, wherein the at least one lateral working unit is positioned at the rear of the motor vehicle.

Claim 20 (New): A mower as claimed in Claim 12, wherein the sensor additionally allows yaw angle of the motor vehicle to be measured.

Claim 21 (New): A mower as claimed in Claim 12, wherein the control device further comprises a detection means for informing the driving unit when the at least one working unit has reached a central position.

Claim 22 (New): A mower as claimed in Claim 21, wherein the detection means comprises a position sensor configured to measure the transverse position of the at least one working unit with respect to the motor vehicle.